

NAG C Library Function Document

nag_dsprtf (f07pdc)

1 Purpose

nag_dsprtf (f07pdc) computes the Bunch–Kaufman factorization of a real symmetric indefinite matrix, using packed storage.

2 Specification

```
void nag_dsprtf (Nag_OrderType order, Nag_UploType uplo, Integer n, double ap[],
                Integer ipiv[], NagError *fail)
```

3 Description

nag_dsprtf (f07pdc) factorizes a real symmetric matrix A , using the Bunch–Kaufman diagonal pivoting method and packed storage. A is factorized as either $A = PUDU^T P^T$ if **uplo** = **Nag_Upper**, or $A = PLDL^T P^T$ if **uplo** = **Nag_Lower**, where P is a permutation matrix, U (or L) is a unit upper (or lower) triangular matrix and D is a symmetric block diagonal matrix with 1 by 1 and 2 by 2 diagonal blocks; U (or L) has 2 by 2 unit diagonal blocks corresponding to the 2 by 2 blocks of D . Row and column interchanges are performed to ensure numerical stability while preserving symmetry.

This method is suitable for symmetric matrices which are not known to be positive-definite. If A is in fact positive-definite, no interchanges are performed and no 2 by 2 blocks occur in D .

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = **Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.
Constraint: **order** = **Nag_RowMajor** or **Nag_ColMajor**.
- 2: **uplo** – Nag_UploType *Input*
On entry: indicates whether the upper or lower triangular part of A is stored and how A is to be factorized, as follows:
 if **uplo** = **Nag_Upper**, the upper triangular part of A is stored and A is factorized as $PUDU^T P^T$, where U is upper triangular;
 if **uplo** = **Nag_Lower**, the lower triangular part of A is stored and A is factorized as $PLDL^T P^T$, where L is lower triangular.
Constraint: **uplo** = **Nag_Upper** or **Nag_Lower**.
- 3: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.

4: **ap**[*dim*] – double *Input/Output*

Note: the dimension, *dim*, of the array **ap** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$.

On entry: the symmetric indefinite matrix *A*, packed by rows or columns. The storage of elements a_{ij} depends on the **order** and **uplo** parameters as follows:

- if **order** = **Nag_ColMajor** and **uplo** = **Nag_Upper**,
 a_{ij} is stored in **ap**[(*j* – 1) × *j*/2 + *i* – 1], for $i \leq j$;
- if **order** = **Nag_ColMajor** and **uplo** = **Nag_Lower**,
 a_{ij} is stored in **ap**[(2*n* – *j*) × (*j* – 1)/2 + *i* – 1], for $i \geq j$;
- if **order** = **Nag_RowMajor** and **uplo** = **Nag_Upper**,
 a_{ij} is stored in **ap**[(2*n* – *i*) × (*i* – 1)/2 + *j* – 1], for $i \leq j$;
- if **order** = **Nag_RowMajor** and **uplo** = **Nag_Lower**,
 a_{ij} is stored in **ap**[(*i* – 1) × *i*/2 + *j* – 1], for $i \geq j$.

On exit: *A* is overwritten by details of the block diagonal matrix *D* and the multipliers used to obtain the factor *U* or *L* as specified by **uplo**.

5: **ipiv**[*dim*] – Integer *Output*

Note: the dimension, *dim*, of the array **ipiv** must be at least $\max(1, \mathbf{n})$.

On exit: details of the interchanges and the block structure of *D*.

More precisely, if **ipiv**[*i* – 1] = *k* > 0, d_{ii} is a 1 by 1 pivot block and the *i*th row and column of *A* were interchanged with the *k*th row and column.

If **uplo** = **Nag_Upper** and **ipiv**[*i* – 2] = **ipiv**[*i* – 1] = –*l* < 0, $\begin{pmatrix} d_{i-1,i-1} & d_{i,i-1} \\ d_{i,i-1} & d_{ii} \end{pmatrix}$ is a 2 by 2 pivot block and the (*i* – 1)th row and column of *A* were interchanged with the *l*th row and column.

If **uplo** = **Nag_Lower** and **ipiv**[*i* – 1] = **ipiv**[*i*] = –*m* < 0, $\begin{pmatrix} d_{ii} & d_{i+1,i} \\ d_{i+1,i} & d_{i+1,i+1} \end{pmatrix}$ is a 2 by 2 pivot block and the (*i* + 1)th row and column of *A* were interchanged with the *m*th row and column.

6: **fail** – NagError * *Output*

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = *<value>*.
 Constraint: **n** ≥ 0.

NE_SINGULAR

The block diagonal matrix *D* is exactly singular.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter *<value>* had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

If **uplo** = **Nag_Upper**, the computed factors U and D are the exact factors of a perturbed matrix $A + E$, where

$$|E| \leq c(n)\epsilon P|U||D||U^T|P^T,$$

$c(n)$ is a modest linear function of n , and ϵ is the *machine precision*.

If **uplo** = **Nag_Lower**, a similar statement holds for the computed factors L and D .

8 Further Comments

The elements of D overwrite the corresponding elements of A ; if D has 2 by 2 blocks, only the upper or lower triangle is stored, as specified by **uplo**.

The unit diagonal elements of U or L and the 2 by 2 unit diagonal blocks are not stored. The remaining elements of U or L overwrite elements in the corresponding columns of A , but additional row interchanges must be applied to recover U or L explicitly (this is seldom necessary). If **ipiv**[$i - 1$] = i , for $i = 1, 2, \dots, n$ (as is the case when A is positive-definite), then U or L are stored explicitly in packed form (except for their unit diagonal elements which are equal to 1).

The total number of floating-point operations is approximately $\frac{1}{3}n^3$.

A call to this function may be followed by calls to the functions:

nag_dspttrs (f07pec) to solve $AX = B$;

nag_dspcon (f07pgc) to estimate the condition number of A ;

nag_dsptri (f07pj) to compute the inverse of A .

The complex analogues of this function are nag_zhptrf (f07prc) for Hermitian matrices and nag_zsptf (f07qrc) for symmetric matrices.

9 Example

To compute the Bunch–Kaufman factorization of the matrix A , where

$$A = \begin{pmatrix} 2.07 & 3.87 & 4.20 & -1.15 \\ 3.87 & -0.21 & 1.87 & 0.63 \\ 4.20 & 1.87 & 1.15 & 2.06 \\ -1.15 & 0.63 & 2.06 & -1.81 \end{pmatrix},$$

using packed storage.

9.1 Program Text

```
/* nag_dsptf (f07pdc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer ap_len, i, j, n;
    Integer exit_status=0;
    Nag_UploType uplo_enum;
```

```

NagError fail;
Nag_OrderType order;

/* Arrays */
char  uplo[2];
Integer *ipiv=0;
double *ap=0;

#ifdef NAG_COLUMN_MAJOR
#define A_UPPER(I,J) ap[J*(J-1)/2 + I - 1]
#define A_LOWER(I,J) ap[(2*n-J)*(J-1)/2 + I - 1]
  order = Nag_ColMajor;
#else
#define A_LOWER(I,J) ap[I*(I-1)/2 + J - 1]
#define A_UPPER(I,J) ap[(2*n-I)*(I-1)/2 + J - 1]
  order = Nag_RowMajor;
#endif

INIT_FAIL(fail);
Vprintf("f07pdc Example Program Results\n\n");

/* Skip heading in data file */
Vscanf("%*[\n] ");
Vscanf("%ld%*[\n] ", &n);
ap_len = n*(n+1)/2;

/* Allocate memory */
if ( !(ipiv = NAG_ALLOC(n, Integer)) ||
     !(ap = NAG_ALLOC(ap_len, double)) )
  {
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
  }

/* Read A from data file */
Vscanf(" ' %1s '%*[\n] ", uplo);
if (*(unsigned char *)uplo == 'L')
  uplo_enum = Nag_Lower;
else if (*(unsigned char *)uplo == 'U')
  uplo_enum = Nag_Upper;
else
  {
    Vprintf("Unrecognised character for Nag_UploType type\n");
    exit_status = -1;
    goto END;
  }
if (uplo_enum == Nag_Upper)
  {
    for (i = 1; i <= n; ++i)
      {
        for (j = i; j <= n; ++j)
          Vscanf("%lf", &A_UPPER(i,j));
        Vscanf("%*[\n] ");
      }
  }
else
  {
    for (i = 1; i <= n; ++i)
      {
        for (j = 1; j <= i; ++j)
          Vscanf("%lf", &A_LOWER(i,j));
        Vscanf("%*[\n] ");
      }
  }
/* Factorize A */
f07pdc(order, uplo_enum, n, ap, ipiv, &fail);
if (fail.code != NE_NOERROR)
  {
    Vprintf("Error from f07pdc.\n%s\n", fail.message);
    exit_status = 1;
  }

```

```

        goto END;
    }
    /* Print factor */
    x04ccc(order, uplo_enum, Nag_NonUnitDiag, n, ap,
           "Factor", 0, NAGERR_DEFAULT);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from x04ccc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Print pivot indices */
    Vprintf("\nIPIV\n");
    for (i = 1; i <= n; ++i)
        Vprintf("%6ld%s", ipiv[i-1], i%7==0 ?"\n":" ");
    Vprintf("\n");
END:
    if (ap) NAG_FREE(ap);
    if (ipiv) NAG_FREE(ipiv);
    return exit_status;
}

```

9.2 Program Data

```

f07pdc Example Program Data
  4                               :Value of N
  'U'                             :Value of UPLO
  2.07    3.87    4.20   -1.15
           -0.21    1.87    0.63
                   1.15    2.06
                           -1.81   :End of matrix A

```

9.3 Program Results

f07pdc Example Program Results

```

Factor
      1          2          3          4
1      2.0700    4.2000    0.2230    0.6537
2          1.1500    0.8115   -0.5960
3          -2.5907    0.3031
4          0.4074

IPIV
  -3    -3     3     4

```
